Yamaha LSI Specifications

YAS539-PZE2 Device Name:

Specification No.: Reference

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Yamaha Stamp			Yamaha Corporation						
		203 Matsunokijima, Iwata, Shizuoka 438-0192, Japan TEL. +81-539-62-4918				2, Japan			
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1. Basic Specifications

- 1. Device Name : YAS539-PZE2
- 2. Function : YAS539 (MS-3S) chip integrates a three axis magnetometer with processing circuits with I2C bus interface to report processed, ready-to-use geomagnetic field intensity values to the host.
- 3. Application : Compass for Mobile phone, Portable GPS system, and so on
- 4. Production process : Si-Gate CMOS process + Magnetic Sensor
- 5. Package : 4-ball WLCSP package (Lead-free solder ball)

2. Block Diagram



Magnetic Sensor

YAS539 has magnetic sensors.

Temperature Sensor

Temperature sensor element is used to correct magnetometer outputs for temperature variations.

A/D Converter

Analog to digital converter digitizes magnetometer and temperature sensor output signals.

Clock Generator

On chip clock generator generates and provides clock signals to internal circuits.

3. Pin Descriptions

Pin Arrangement



4 pin WLCSP

Pin Descriptions

Ball No.	Name	I/O	Description
1A	SCL	Is	I2C serial clock
1B	VDD	-	Power (1.8 V typ.)
2A	SDA	Is/Od	I ² C serial data
2B	VSS	-	Ground

Is : Schmitt trigger input

 $Od ~~: Open\mbox{-} drain \mbox{ outpu}$

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4. Electrical Characteristics

Absolute Maximum Ratings

Parameter	Symbol	Min.	Тур.	Max.	Unit
Supply Voltage (VDD)	V _{VDD}	-0.3		2.5	V
Digital Input Pin Voltage (SCL, SDA)	V _{IND}	-0.3		2.5	V
Storage Temperature	T _{stg}	-50		125	°C
Maximum Applicable Magnetic Field Intensity	H _{max}			500	mT

Recommended Operating Conditions

Parameter	Symbol	Min.	Тур.	Max.	Unit
Supply Voltage (VDD)	V _{VDD}	1.65	1.8	1.95	V
Operating Ambient Temperature	T _{OP}	-40	25	85	°C

Note: The above operating conditions do not always ensure data sampling accuracy. In an actual application, the ambient magnetic environment may vary with changes in temperature and affect data sampling accuracy.

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Operating Current

Parameter	Min.	Тур.	Max.	Unit
Standby current($T_{OP} = 25^{\circ}C$, SCL = SDA = VDD = 1.95 V)			1.5	μΑ
Standby current($T_{OP} = 85^{\circ}C$, SCL = SDA = VDD = 1.95 V)			15	μΑ
Current drawn during standby (periodic sampling)		10		μΑ
Current drawn during magnetometer data sampling (See Note 1.)		2.5		mA
Current drawn during temperature data sampling (See Note 1.)		1.5		mA
Current averaged during periodic sampling (Default configuration, VDD = 1.8 V, 100 sample/s)		280		μΑ
Current averaged during periodic sampling (See Note 2.) (Low current configuration, VDD = 1.8 V, 100 sample/s)		160		μΑ
Current during activating reset coils		95		mA

Note 1: After data sampling, the device automatically powers down to enter the standby state. Note 2: See 9.2.6. AVRR: Averaging Filter for further information.

Magnetic Sensor Characteristics

		(Cond	itions: T _{OP}	$= 25^{\circ}C, V$	DD = 1.8 V)
Parameter		Min.	Тур.	Max.	Unit
Maximum measurable magnetic field intensity	(See Note 1.)	-	2000	-	μΤ
Magnetic field sensitivity (X, Y, Z)	(See Note 2.)	-	0.15	0.3	$\mu T / LSB$
Sensitivity axis deviation	(See Note 3.)	-	-	±5	deg

Note 1: This value assumes Yamaha device driver is used.

Note 2: Y sensitivity is for $(Y1 - Y2) / \sqrt{3}$, and Z sensitivity for -Y1 - Y2.

Note 3: The sensitivity axis deviation is for the value corrected with CAL register values without magnetic fields.

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4. Electrical Characteristics

Data Sampling Time

(Conditions: $T_{OP} = 25^{\circ}C$, VDD = 1.8 V)

Parameter	Min.	Тур.	Max.	Unit
Data Sampling Time	-	1.10	1.21	ms
On-chip oscillator frequency tolerance			±10	%

* The sampling time assumes registers have initial values, and varies depending on what value registers have.

DC Characteristics

	(For oper	ation under Recomme	nded Operating Co	onditions)
Parameter	Symbol	Min.	Max.	Unit
"L" level input voltage	V _{IL}	-0.3	$0.3 \times V_{\rm VDD}$	V
"H" level input voltage	V_{IH}	$0.7 imes V_{VDD}$	$V_{VDD} + 0.3$	V
Hysteresis voltage width (SCL, SDA)	V _{SH}	$0.1 \times V_{VDD}$		V
"L" level output voltage (sink current 3 mA)	V _{OL}	0	$0.2 \times V_{\rm VDD}$	V
Input leakage current at the input voltage ranging from $0.1 \times VVDD$ to $0.9 \times VVDD$	Ii		±1	μΑ
I/O pin static capacitance	Ci		10	pF

4. Electrical Characteristics

AC Characteristics

Power Supply Timing

(For op	eration und	ler Recommende	ed Operating Co	onditions
Parameter	Symbol	Min.	Max.	Unit
Power supply ramp up time (VDD)	T _{VON}	0.01	50	ms
Time taken from when VDD gets valid to when I2C gets ready	T _{DOP}	-	4	ms
T _{VON}				



4. Electrical Characteristics

Serial Data Interface: SCL, SDA

	(For operation	on under Recommer	nded Operating (Conditions)			
Parameter	Symbol	Min.	Max.	Unit			
Input Conditions							
SCL clock frequency	f_{SCL}	0	400	kHz			
(Repeated) START bit hold time	t _{HD;STA}	0.6		μs			
SCL clock "L" time	$t_{\rm LOW}$	1.3		μs			
SCL clock "H" time	t _{HIGH}	0.6		μs			
Repeated START bit setup time	t _{SU;STA}	0.6		μs			
Data hold time	t _{HD;DAT}	0	0.9	μs			
Data setup time	t _{SU;DAT}	0.1		μs			
SDA or SCL signal rise time	t _r		300	ns			
SDA or SCL signal fall time	t _f		300	ns			
STOP bit setup time	t _{SU;STO}	0.6		μs			
Bus free time between STOP and START bits	t _{BUF}	1.3		μs			
SDA and SCL capacitive load	C _b		400	pF			
Output Conditions	Output Conditions						
SDA fall delay time	t _{DSDAL}		1.15	μs			
Data output hold time	t _{HD;DAT}	0	0.9	μs			



Serial Data Interface Timing.

- YAS539 serial data interface is compliant to I²C as much described in this document.
- The circuit tolerates spike noise of up to about 50 ns.

5. Function Overview

YAS539 (MS-3S) chip integrates a three axis magnetometer with processing circuits with I2C bus interface to report processed, ready-to-use geomagnetic field intensity values to the host.

The chip features high sensitivity, low noise magnetic field sensor elements which works with lower voltage across the sensing bridge circuit, allowing single 1.8 V operation. Like our previous generation devices, the chip samples magnetic field periodically in a short time and then goes into power down state by itself, but when coupled with its lower voltage operation, achieves further power saving compared to them.

Packaged in 0.97 mm \times 0.97 mm WLCSP, one of the smallest on the market, and less area required as fewer additional discrete components thanks to the single supply operation, the chip as well improves system footprint over the previous devices.

The chip provides averaging filter for low noise sampling while keeping power consumption low and supports periodic data sampling, allowing flexible configurations for various applications.

On-chip memory contains sensor element errors found at chip factory which can be used to effortlessly reduce errors. YAS539 chip thus makes a compact, feature-rich electronic compass part with high sensitivity and low power consumption for mobile phone and GPS applications.

- Three-axis magnetometer and processing circuits in one package
- Geomagnetic field sensor elements superior sensitivity and higher S/N ratio
- Small sized package
- 1.8 V single power supply operation with minimum external component counts
- Automatic power-down controls
- Low power consumption
- Autonomous periodic sampling (sampling and processing data at set time intervals)
- Configurable averaging filters for reducing noise level and saving power
- I2C bus interface (100 kbps / 400 kbps, slave mode)

Package	Pb-free 4-ball WLCSP (YAS539-PZ)			
Size	0.97mm × 0.97 mm			
Power Supply (VDD)	1.65 V to 1.95 V			
Operating temperature	-40° C to $+85^{\circ}$ C			
Averaged current	$280 \ \mu A$ (Default configuration; 100 sample/s, VDD = 1.8 V)			
(See Note 1.)	160 μA (Low current mode; 100 sample/s, VDD = 1.8 V)			
Magnetometer				
Manufacturing process	Standard CMOS + Magnetic sensor element process			
Maximum intensity	2000 μΤ	(See Note 2.)		
Sensitivity (X, Y, Z)	0.15 μT / LSB			
Sampling time	1.1ms (magnetic field intensity + temperature sampling)	(See Note 3.)		

Note 1: For details of the Low Current Mode

Note 2: With Yamaha-provided device driver used.

Note 3: Different register configuration needs different time to complete one sampling. The value shown is for default configuration.on.

6. Markings

(REG.No. U-M4P-ZG6401-Z*)



Specification No. : Reference

7. Package Outlines

(REG.No. U-PK4PP3-18-2)



The value parenthesized is not specified.

外形寸法はバリを含みます。 Dimensions include burr.

UNIT: mm

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(REG.No. U-F-260C0-04)

8. Cautions for use of the surface mount package

使用上の注意 / Precaution for soldering

WLCSP パッケージ下面の半田端子(ボール)を溶融して、半田付け実装してください。また、製品耐熱性を考慮して、パッケー ジ本体の表面温度管理を行ってください。具体的な使用条件は下記をご参照ください。

Dissolve the solder terminal (ball) of WLCSP package undersurface and carry out solder mounting. Moreover, control the temperature of package surface in consideration of product heat resistance. Refer to the following for the concrete handling condition.

1. 実装までの保管 / Storage before soldering

吸湿及び端子の酸化を避けるため、実装するまでは出来るだけ乾燥した雰囲気中に保管してください。推奨条件は下記のとおり です。

Store the products in the environment which is as dry as possible to prevent moisture absorption and oxidation of terminal, until soldering. We recommend the following conditions.

温度 / Temperature		5∼30°C /5°C to 30°C
	湿度 / Humidity	70%RH.以下 /Less than 70% RH.

防湿梱包開封後の取り扱い / Handling after the dry packing bag is opened

開封後は吸湿および端子底面の酸化を避けるため、上記環境条件下にて保管し、リフロー半田付け実装してください。 開封後に再保管される場合も上記環境条件下で保管してください。(耐湿レベルは J-STD-020 LEVEL1 を有しております。) Store in accordance with the condition described above to avoid moisture absorption and the oxidation of terminal after opening the dry packing, and carry out reflow soldering. If stored again after opening, store under the conditions described above. (J-STD-020 : MSL LEVEL1)

3. 半田付け条件 / Soldering conditions







アンダーフィル / Underfill

アンダーフィルを行うと温度補正が正常に行われない可能性がありますのでアンダーフィル無しで実装してください。

Since temperature compensation may not be performed normally when under-fill is made while mounting WLCSP on a board, please mount it without under-fill.

9. Yamaha LSI Application Notes

Yamaha LSI Application Notes

The most of Yamaha LSIs are manufactured by the C-MOS process technology. When using these LSIs, please keep the following instructions:

- Fix the unused input to H or L.

Connect the unused input terminal to the power supply or ground terminal.

When the terminal voltage becomes the middle potential, both P-gate and N-gate are turned on and flows the penetrating current.

Even for the terminal internally pulled-up, it should be connected to the power supply terminal for noise immunity. On the other hand, the unused output terminal should be remained unconnecting.

- Pay attention to the latch-up

Any input signal shall not exceed the power supply range.

When a terminal voltage rises more than the power supply voltage or falls less than the ground voltage, a parasitic thyristor is induced and it causes latch-up.

This will damage the LSI or will be deteriorated of reliability.

Especially, note that any signal voltage shall not be previously applied before power supply voltage is supplied.

- Supply the same power voltage to the power supply terminals.

Use identical power supply to provide to each power supply terminal.

The potential difference between these terminals causes short-circuits and latch-up, because most of the power supply terminals of the monolithic LSI are connected each other internally.

- Don't shut the clock signals.

Don't shut the clock signals supplied to the LSI while working.

Many dynamic circuits are often used for high integration in Yamaha LSIs.

The dynamic circuits may induce penetrating current by being gone its charge with the shutting the clock signals. The penetrating current causes damage of the LSI.

- Warning for the device which makes sound using speaker

A speaker radiates heat in a voice-coil by air flow accompanying vibration of a diaphragm. When DC signal (several Hz or less) is input, heat radiation characteristics falls rapidly.

In addition, even if it is used lower than rated input, it may lead to voice-coil burnout, smoke or ignition of a speaker.

In order to avoid such situations, be sure to implement one or more preventive measures from the following.

- 1. Do not select settings (sound production) which may generate DC signal.
- (Since thoroughness of this preventive measure is generally difficult, we recommend the combined use with the following 2, 3, and 4)
- 2. Add the equivalent of DC cut digital filter for cutting DC signal in the digital section.
 - (As long as "Built-in" is not mentioned in the manual, there is no such built-in circuit inside of a device).
- 3. Add a DC cut capacitor for cutting DC signal in the analog section.

(When addition is specified in the example of a recommended circuit diagram, be sure to add)

4. When a latter stage device exists in the signal path from this device to speaker, be sure to realize the DC cut in a latter stage device.

In addition, the above-mentioned measures are based on the assumption that the device itself, DC cut capacitor, and the latter stage device will be in a normal operation. Therefore, it is also necessary to implement measures based on the assumption of these part failures.

9. Yamaha LSI Application Notes

PRECAUTIONS AND INSTRUCTIONS FOR SAFETY

WARNING

Do not use the device under stresses beyond those listed in Absolute Maximum Ratings. Such stresses may become causes of breakdown, damages, or deterioration, causing explosion or ignition, and this may lead to fire or personal injury.

Prohibited

Prohibited

Prohibited

Instructions

Do not mount the device reversely or improperly and also do not connect a supply voltage in wrong polarity. Otherwise, this may cause current and/or power-consumption to exceed the absolute maximum ratings, causing personal injury due to explosion or ignition as well as causing breakdown, damages, or deterioration. And, do not use the device again that has been improperly mounted and powered once.

Do not short between pins. In particular, when different power supply pins, such as between high-voltage and low-voltage pins, are shorted, smoke, fire, or explosion may take place.

As to devices capable of generating sound from its speaker outputs, please design with safety of your products and system in mind, such as the consequences of unusual speaker output due to a malfunction or failure. A speaker dissipates heat in a voice-coil by air flow accompanying vibration of a diaphragm. When a DC signal (several Hz or less) is input due to device failure, heat dissipation characteristics degrade rapidly, thereby leading to voice-coil burnout, smoking or ignition of the speaker even if it is used within the rated input value.



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10. Packing specification

(REG.No. U-PC4PP4-03)

WLCSP4 梱包仕様書 / WLCSP4 Packing specifications

No.	Japanese		English		
1	エンボスキャリアテープ	導電性PC製	Embossed carrier tape	Conductive PC	
2	カバーテープ	帯電防止フィルム製	Cover tape	Antistatic film	
3	リール	導電性PS製	Reel	Conductive PS	
4	内袋	透明静電袋	Inner bag	Transparent electrostatic bag	
5	ラベル	品名・数量を表示	Label	Part name and quantity	
6	内箱	段ボール製	Inner box	Cardboard	
\overline{O}	クッション材	段ボール製	Cushioning material	Cardboard box	
8	外箱	段ボール製	Outer box	Cardboard	

<収納個数 / Storage quantity>

リール/Reel	IC 10000 +5/-0 pcs. / reel		
外箱/Outer box	Max 5 inner boxes / outer box		

<仕様 / specification>

(1)部品の欠落数 / Maximum blank pockets

部品の欠落数は、リールの総部品数の0.05%又は1個のいずれか大きい方以下とし、連続2個以上の欠落はないものとする。 Each reel shall contain a maximum of 0.05% or 1 blank pocket, whichever is greater. Two or more successive blank pockets shall not be allowed.

(2) エンボスキャリアテープの引っ張り強度 / Tensile strength of embossed carrier tape
10N以上とする。 / The embossed carrier tape shall have a tensile strength of 10N or greater.

(3)カバーテープの剥離強度 / Peel strength of cover tape

テープ接着面に対し165~180度で毎分300mmの速さで剥離させた時0.1~1.0Nとする。

The cover tape shall have a peel strength of 0.1 to 1.0N when peeled at an angle between 165 to 180 degrees relative to the adhesive face of the tape and at a speed of 300mm per minute.

(4)包装 / Packing

テーピングの終了したリールには、製品名、ロットNo.、梱包日、数量等を記入したラベルを貼り、内袋に入れ ヒートシールする。

Each reel complete with the taping procedure shall have a marking label posted on it; each label shall have the indications of Product name, quantity, lot number, packing date. The reel shall be put into an inner bag, which shall be heat sealed.

Specification No. : Reference

(REG.No. U-PC4PP4-03)

10. Packing specification

●梱包説明図 / Explanatory Drawing for Packing specification

 $3 \sim 1 \sim 2$ Inner boxes



Specification No. : Reference

10. Packing specification

●リール、エンボスキャリアテープ寸法 / Dimensions of Reel and Embossed carrier Tape



●リーダー部、終端部寸法 / Dimensions of Tape Leader Part and Tape End Part



(REG.No. U-PC4PP4-03)

信頼性試験結果成績書 Reliability Test Result



製品名 Product Name	YAS539-PZE2
パッケージ Package Type	WLCSP4
試験番号 Test No.	R3279

	試験項目 Test Item	参考規格 Reference Standard	条件 Condition		不良数 / 試験数 Failure / Sample Size
1	高温通電試験 High Temperature Operating	JEITA ED-4701/101 JEDEC JESD22-A108	Ta=125°C, VDD=VDDMAX t=1000h		0/15
2	高温保存試験 High Temperature Storage	JEITA ED-4701/201 JEDEC JESD22-A103	Ta=150°C t=1000h		0/15
3	はんだ耐熱性試験 Resistance to Soldering Heat	JEITA ED-4701/301 IPC/JEDEC J-STD-020	Precondition : MSL 1 265°C Peak IR-Reflow 3 times		0/45
4	高温高湿通電試験 (はんだ耐熱性試験後) High Temperature High Humidity Operating (After item Resistance to Soldering Heat)	JEITA ED-4701/102 JEDEC JESD22-A101	Ta=85°C, RH=85%, VDD=VDDMAX t=1000h		0/15
5	プレッシャークッカー試験 (はんだ耐熱性試験後) Pressure Cooker (After item Resistance to Soldering Heat)	JEITA ED-4701/103 JEDEC JESD22-A118	Ta=130°C, RH=85%, 2.3 atm t=96h		0/15
6	温度サイクル試験 (はんだ耐熱性試験後) Temperature Cycling (After item Resistance to Soldering Heat)	JEITA ED-4701/105 JEDEC JESD22-A104	-65°C / R. T /150°C (30min / 5min /30min) 500 cycles		0/15
7	静電破壊試験 人体モデル ESD Human Body Model (HBM)	JEITA ED-4701/300 JEDEC JESD-22-A114	C=100pF, R=1.5kΩ, ±2000V, 1time	ground : VDD ground : VSS	0/5 0/5
8	静電破壊試験 マシンモデル ESD Machine Model (MM)	JEITA ED-4701/300 JEDEC JESD-22-A115	C=200pF, R=0Ω, ±200V, 1time	stress (+) stress (-)	0/5 0/5
9	静電破壊試験 デバイス帯電モデル ESD Charged Device Model (CDM)	JEITA ED-4701/300 JEDEC JESD-22-C101	F-CDM ±500V, 1time	stress (+) stress (-)	0/5 0/5
10	ラッチアップ試験 コンデンサディスチャージ法 Latch-up (Condenser discharge)	-	C=500pF, R=470Ω, ±150V	stress (+) stress (-)	0/5 0/5